Design And Implementation Of Multiposes Face Recognition System

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Abstract- Digital pictures are getting additional vital within the transmission information. The external body part is one amongst the foremost vital objects in a picture. Investigation of crime is the situation of human faces then extracting the facial feature in a picture is a very important ability with big selection of applications, like external body part recognition, human pc interfacing. The face detection algorithmic program uses each frontal face and profile face detectors by extracting the ‘Haar’ options and uses them in a very cascade of boosted classifiers. The set from the face detection algorithmic program that uses a mixture of profile and frontal face cascades and, counting on the create, the face is compared with a specific set of faces having identical vary for classification. The detected faces are recognized by projected them onto the obtained the particular section victimization standard weighted PCA. During this system, create vary is split into 3 bins onto that the faces are sorted. This method has the advantage of recognizing a personal with minimum false positives attributable to create variations.

Keywords- Face Recognition, Machine Learning, Classification, Genetic algorithm

1. Introduction

Human face perception is presently a vigorous analysis area inside the computer vision community. Detection the location of human faces therefore extracting the countenance in an exceedingly image could be a vital ability with an honest varies of applications. Face detection is that the essential for part of any face recognition system that locates the face regions from pictures. It additionally has various applications areas like police investigation and security management systems, content-based image retrieval, video conferencing and intelligent human-computer interfaces. Face recognition has been one in every of the for most interesting and important research fields within the past twenty years.

Human face perception is presently a vigorous analysis area inside the computer vision community. Detection the location of human faces therefore extracting the countenance in an exceedingly image could be a vital ability with an honest varies of
applications. Face recognition is that the strategy of automatically determinant whether or not or not 2 faces unit of measurement constant person. Sort of things produce this troublesome drawback for computers. Faces in footage and video square measure typically captured at varied resolutions, quality, and lighting conditions. Utterly totally different (completely different) cameras have different imaging properties. Moreover, people’s facial expressions likewise as their produce with regard to the camera can vary wide, and facial characteristics can modification dramatically as people age over time.

Digital footage and video became extra necessary inside the multimedia information era. The face is one in each of the foremost necessary objects in an exceedingly image or video. police work the location of human faces thus extracting the facial feature in an exceedingly image could be a important ability with wide range of applications, like face recognition, police investigation systems, human portable computer interfacing, video-conferencing etc.

In this work, it's enforced a personality's face recognition technique by Genetic algorithmic program [2]. Genetic algorithmic programs area unit a random search algorithm that uses chance to guide the search. It will notice the close to world best resolution in an exceedingly high resolution area quickly. It's been used extensively in several application areas, like image process, pattern recognition, face detection, feature choice, and machine learning. Its power comes from its ability to mix sensible items from totally different resolutions and assemble them into one super solution.

Our aim, that we have a tendency to believe to get reached, was to develop a way of face recognition that's quick, robust, fairly straightforward and correct with a comparatively straightforward to grasp algorithms and techniques. Given a picture, the goal of face sight ion algorithmic program is to detect the face and extract the options from given image and to acknowledge the detected face with given info of face pictures that is trained by artificial Neural Network victimization Genetic algorithmic program [3,4,5].

II. Literature Survey
There are a unit numerous approaches projected by numerous researchers for image based mostly face recognition. during this chapter a quick description of those approaches and a comparison between them area unit given:

Support Vector Machine:
In 1997, Osuna, Freund, and Girosi [6] have recently investigated face detection victimization a framework. However, they use a “support vector machine” to classify pictures, instead of a clustering-based technique or a neural network. The support vector machine encompasses a range fascinating properties, together with the actual fact that it makes the boundary between face and non-face pictures additional specific. The results of their system, the accuracy is currently slightly poorer.

Evolution. Pursuit Approach:
In 2000, biological process Pursuit (EP), a completely unique accommodative illustration technique, and showed its practicability for the face recognition downside. EP seeks to find out associate optimum basis for the twin purpose of knowledge compression and pattern classification. Face projections appropriate for compact and economical face encryption in terms of each gift and future recognition ability. The prediction risk, enclosed as a penalty, may be a live of g

Eigen face-based Recognition Approach:
In 2001, Kwok-Wai Wong, Kin-Man Lam proposed a additional reliable face detection approach supported the genetic formula and Eigen face technique [8]. Firstly, potential eye candidates are obtained by sleuthing the vale points. based mostly on a try of eye candidates, potential face regions area unit generated by genetic formula. every of the possible face candidates is normalized by approximating the baking angle attributable to head movement. The lighting impact is reduced by reworking their bar graphs into the histogram of reference face image. The fitness price of face candidate is calculated by jutting it onto the eigen faces. Selected face candidates are then additional verified by mensuration their symmetries and determining the existence of various countenance .however limitation is that the edge price for single-face detection is larger than that for multiple-faces detection.

Detection rate for multiple faces is poor. Conjointly there's an alternative analysis on eigen space-based face recognition [9].

Hausdorff Distance Approach:
In 2001, a face detection system that works with edge options of grayscale pictures and therefore the modified Hausd or ff Distance. when detection of facial region, face position parameters area unit refined in a very second section. System performance has been examined on 2 massive check sets by comparing eye positions calculable by the system against manually set ones with a relative error live that's freelance of each the dimension of input images and the size of faces. the great localization results show
that system is robust against different background conditions and ever-changing illumination, however there are unit restrictions of detection of solely frontal views and single faces, on automatic model creation and transformation parameter improvement [10].

In 2002, Meng, Shiqian Wu, and Juwei Lu projected a way Radial Basis operate of Neural Network. a general style approach victimisation associate RBF neural classifier for face recognition to deal with tiny coaching sets of high-dimensional problem is bestowed. Firstly, face options area unit 1st extracted by the PCA, then the ensuing options area unit additional projected into the Fisher’s optimum topological space during which quantitative relation of the between-class scatter and within-class scatter is maximized. coaching knowledge data is employed in the choice of structure and parameters of RBF neural networks before learning takes place, is bestowed. Finally, hybrid learning algorithm is projected to coach the RBF neural networks. Simulation results show that the system achieves glorious performance each in terms of error rates of classification and learning efficiency. These experiments show that if the variance of noise is little, there's no impact on generalization, whereas massive variance of noise can deteriorate the performance[11].

Independent part Analysis Approach:
In 2003, Chengjun Liu associated Harry Wechsler introduced an freelance physicist options (IGF) technique for face recognition. The IGF technique derives 1st a physicist feature vector based mostly upon a group of down sampled Gabor moving ridge representations of face pictures by incorporating completely different orientation and scale native options. freelance part analysis operates then on the physicist feature vector, who sedimensionality has been reduced by PCA, and derives freaelancephysicist options. Finally, the in dependence property of freelance physicist options ends up in associate application of the PRM method for classification. On one hand, physicist reworked facepictures exhibit robust characteristics of spatial neighborhood, scale and orientation property, the same as those displayed by physicist wavelets. It produces salient native options in neighborhood of the eyes, nose and mouth that area unit most fitted for face recognition. On the opposite hand, ICA would additional sight redundant options. The IGF technique facilitates automatic implementations a result of it doesn't involve non-trivial manual annotation of form points[12].

In 2006, Linlin Shen and Li Tibeto-Burman introduced a review on physicist wavelets for face recognition [13]. second physicist wavelets introduced that the way to use them for native feature extraction. In face recognition. Face image might be pictured by the physicist jets extracted at some pre-defined feature points. Analytical ways utilize the physicist jets extracted from pre-defined feature points on the face pictures for recognition. Completely different approaches to find feature points for physicist jets extraction, classified into 2 categories: For elastic graph based mostly analytic methods, a graph is 1st placed at associate initial location and misshapen victimisation jets to optimize its similarity with a model graph. Non-graph based mostly ways find feature points manually or by color or edge etc. then recognition will then be performed victimisation physicist jets extracted from those feature points. however additional analysis work is needed int he following areas: 1) the way too point for the optimum physicist moving ridge basis. While most of the works area unit following the framework of 5 scales/eight orientations, a large number of works conjointly projected their own style ways. However, most of the ways area unit bestowed while not justification and it remains unclear that one is that the best.2) With no assumptions on locations and parameters of physicist moving ridge basis, associate improvement algorithm able to pick out each the physicist moving ridge basis and jet locations for face illustration is needed. 3) The graph structures accessible for representation of faces area unit comparatively restricted, new structure and graph matching algorithms area unit inspired.4) the eye on physicist moving ridge networks is truly quite restricted.[13].

III. Proposed Methodology
Face recognition system consists of two phases:

1) Database
Detect the human face with the help of raster scanning method. One pixel of an image consists of 24-bits. 24-bits consists of red, green, blue pixels each of 8-bits. Ranges of colors are from 0 to 255. Detect the features of images like skin color and eye. Crop the face and by enhancing it with the help of Gabor filter, Wavelet database and Haar Wavelet and save it into database. With the help of Canny method, Robert method edge of an image can be detected.

2) Face Recognition
Detect the skin region and features of a image and split face into several numbers. According to the features it is divided into three types of features that is strong features, medium features and weak features. Each feature consists of some pixels. Edge of an image can be detected with the help of edge detection method. Compare the matrix of feature of an input image with the matrix of images stored into the database. According to the matching percentage of particular image stored it into filter database. Take an image from filter database and cluster it with the help of C-Fuzzy means. This method gives us percentage of matching. Give indexing to images according to their matching percentage and display the result.
Image Enhancement:

It refers to accentuation, or sharpening, of image features such as boundaries, or contrast to make a graphic display more useful for display & analysis. This process does not increase the inherent information content in data. It includes gray level & contrast manipulation, noise reduction, edge sharpening, filtering, interpolation and magnification, pseudo coloring, and so on. Edge enhancement is an image processing filter that enhances the edge contrast of an image or video in an attempt to improve its acutance. The filter works by identifying sharp edge boundaries in the image, such as the edge between a subject and a background of a contrasting color, and increasing the image contrast in the area immediately around the edge. There are following Image Processing techniques used in this thesis for Image Enhancement i.e. Gabor filter which is used to denoising the image, Haar Wavelet which are used for image enhancement.

Denoise Image Using Gabor Filter

In image processing, a Gabor filter, named after Dennis Gabor, is a linear filter used for edge detection. Frequency and orientation representations of Gabor filters are similar to those of the human visual system, and they have been found to be particularly appropriate for texture representation and discrimination. The Gabor filters are self-similar: all filters can be generated from one mother wavelet by dilation and rotation. The filters are convolved with the signal, resulting in a so-called Gabor space. The Gabor space is very useful in image processing applications such as optical character recognition, iris recognition, human face recognition and fingerprint recognition. Relations between activations for a specific spatial location are very distinctive between objects in an image. Furthermore, important activations can be extracted from the Gabor space in order to create a sparse object representation.

A typical in Gabor filter, A Gabor base function is a Gaussian function modulated with an exponential or sinusoidal function that is defined in terms of the product of a Gaussian and an exponential.

To explain the Gabor denoising procedure, assume \( I[i, j] \) to be the original M by M image where \( i \) and \( j = 1, 2, \ldots, M \) and it is corrupted with additive noise \( n[i, j] \):

\[
S[i, j] = I[i, j] + n[i, j]
\]

\( n[i, j] \) are identically distributed and independent of \( I[i, j] \). The goal of denoising is to estimate \( \hat{I}[i, j] \) of \( I[i, j] \) by removing the noise \( n[i, j] \). In the first step of Gabor denoising, the observed image \( S \) is transformed into the Gabor domain. Then the Gabor coefficients are threshold and finally the denoised coefficients are transformed back to reconstruct the image. The choice of the threshold and the method which is used to calculate the threshold, determine how efficient the denoising technique would be. Although, selecting a small threshold may produce an output image close to the input, the recovered image may still be noisy. On the other hand, a choice of a large threshold may yield a blurred image by setting the most of the wavelet coefficients to zero.

Haar Wavelet Method

The first DWT was invented by the Hungarian mathematician Alfréd Haar in 1909. For an input represented by a list of \( 2^n \) numbers, the Haar wavelet transform may be considered to simply pair up input values, storing the difference and passing the sum. This process is repeated recursively, pairing up the sums to provide the next scale: finally resulting in \( 2^n - 1 \) differences and one final sum. The technical disadvantage of the Haar wavelet is that it is not continuous, and therefore not differentiable. This property can, however, be an advantage for the analysis of signals with sudden transitions, such as monitoring of tool failure in machine.

Figure: Decomposition model of Haar Wavelet
The Haar Wavelet Transformation is also a simple form of compression involved in averaging and differencing terms, storing detail coefficients, eliminating data, and reconstructing the matrix such that the resulting matrix is similar to the initial matrix. A HT decomposes each signal into two components as shown in figure 4.5.1, one is called average (approximation) or trend and the other is known as difference or fluctuation. HT is suitable for application when the image matrix has number of rows and columns as a multiple of 2.

**Pattern Matching Algorithm:**

**Step 1:** Take an input image in m*n form  
**Step 2:** Cluster input image of size k (where k=1, 2, 3, ……m*n)  
**Step 3:** Load faces ‘F’ from database  
**Step 4:** While F=1 to length (Database)  
\[
P = P + 1; \\
T = T + 1;
\]
Cluster image I to 1, 2,…..a*b  
Match I_F with I_P_T  
Calculate Percentage  
\[
P = P + 1; \\
T = T + 1;
\]
End  
**Step 5:** Display result  
**Step 6:** Stop

**Flow Chart Of Face Recognition System**
IV. EXPERIMENTAL RESULTS

Input Image Nidhi

Table-1 Original Image

<table>
<thead>
<tr>
<th>I/p Image</th>
<th>Entropy</th>
<th>Mean Intensity</th>
</tr>
</thead>
<tbody>
<tr>
<td>Nidhi</td>
<td>17.1478</td>
<td>0.59216</td>
</tr>
</tbody>
</table>

Face to be Detected

Time for face detection=0.93727 Sec

Table-2 Reading After Face Detection

<table>
<thead>
<tr>
<th>I/p Image</th>
<th>Entropy</th>
<th>Mean Intensity</th>
</tr>
</thead>
<tbody>
<tr>
<td>Nidhi</td>
<td>17.7186</td>
<td>0.45098</td>
</tr>
</tbody>
</table>

If an image is of large dimensions, we must need to resize it into a dimension of 100 X 100. The reason behind this is that, number of pixels are directly proportional to time required.

\[ P_i \propto T_i \]

Where \( P_i \) = Number of pixels of image
\( T_i \) = Time required

Table-3 Denoise Image Using Gabor Filter

<table>
<thead>
<tr>
<th>I/P Image</th>
<th>Entropy</th>
<th>Mean Intensity</th>
<th>Time for face enhancement</th>
</tr>
</thead>
<tbody>
<tr>
<td>Nidhi</td>
<td>17.4321</td>
<td>0.51765</td>
<td>0.39537</td>
</tr>
</tbody>
</table>
Table 4: Canny Edge Detection

<table>
<thead>
<tr>
<th>I/P Image</th>
<th>Time for Segmentation (Secs)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Nidhi</td>
<td>0.51647</td>
</tr>
</tbody>
</table>

Table 5: Centroid Detection

<table>
<thead>
<tr>
<th>I/P Image</th>
<th>Time for centroid Detection (Secs)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Nidhi</td>
<td>3.3697</td>
</tr>
</tbody>
</table>

Table 6: Features Segmentation

<table>
<thead>
<tr>
<th>I/P Image</th>
<th>Time for features Segmentation (Secs)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Nidhi</td>
<td>0.17159</td>
</tr>
</tbody>
</table>

Number of features Detected - 275

Recognize Image

Total time for face Recognition - 93.3509 Secs

V. Conclusion

The main objective of the proposed scheme is to recognize multiposes face image. In this paper, three levels of face recognition are used. Features of an image are divided into three parts: strong features, medium features, and weak features. According to the number of features detected and located, the face of an image is recognized.

References


