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### **RESEARCH ARTICLE**



# Implementation of Reversible Sequential Circuits Using Conservative Logic Gates

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*Abstract- Reversible circuits do not lose any information during computation. Reversible computation can be performed using reversible gates like fredkin gate, feynmann gate and toffoli gate. It has unique output vector for each input vector and has one to one mapping between the inputs and outputs. The existing system is designed using fredkin gate and they are cascaded in series or parallel using the characteristic equation of each reversible gate. In the proposed system sequential circuits like master slave flip-flop and edge triggered flip-flop are designed using toffoli gate which is universal in nature. These circuits have less power dissipation and are used in applications like quantum computing, digital signal processing, cryptography nanotechnology and testing. The circuit can detect stuck at fault using two test vectors 0 and 1.*

*Keywords - fredkin gate; quantum computing; toffoli gate; stuck at fault; reversible logic*

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## I. INTRODUCTION

Reversible logic appears to be promising due to its wide applications in emerging technologies. Some of the applications of reversible logic are quantum computing, quantum dot cellular automata, optical computing, Spintronics, DNA computing, molecular computing and also in power-efficient nano computing. Reversible circuits are those circuits that do not lose information during computation and reversible computation in a system can be performed only when the system comprises of reversible gates. These circuits can generate unique output vector from each input vector, and there is a one-to-one mapping between the input and the output vectors. In an irreversible gate information is physical and some minimum amount of energy is required per computation step.

**A. Basic reversible gates**

The basic reversible gates are those that create one to one mapping between inputs and outputs. The number of outputs are equal to the number of inputs. These gates do not result in power dissipation and are conservative in nature. The basic reversible gates are the conventional not gate, Feynman gate, Fredkin gate and Toffoli gate.

1) **Feynman gate** :It is a two input and two output gate implemented using the XOR function.

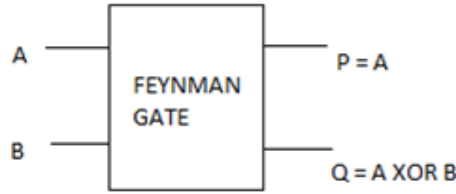


Fig 1 Feyman Gate

2) **Toffoli gate**: The Toffoli gate can be implemented by using the following equations.

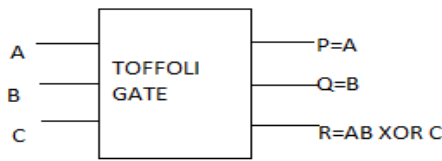


Fig 2 Toffoli Gate

3) **Fredkin gate**: The Fredkin gate or controlled-swap gate, swaps the two inputs B and C if A is true.

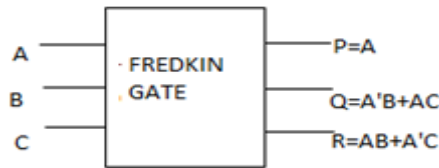


Fig 3 Fredkin Gate

**II. SYSTEM MODEL**

The design of master slave flip-flop and double edge triggered flip-flop are presented using fredkin gate in the existing system

**A. Design of master-slave flip-flops using fredkin gate**

In this design two latches namely negative enable slave latch and positive enable slave latch are cascaded as shown in the Fig. 4. The master positive enable latch is designed using the characteristic equation  $Q^+ = DE + E'Q$  with clock = 1. The slave negative enable latch is designed using the characteristic equation  $Q^+ = DE' + EQ$ .

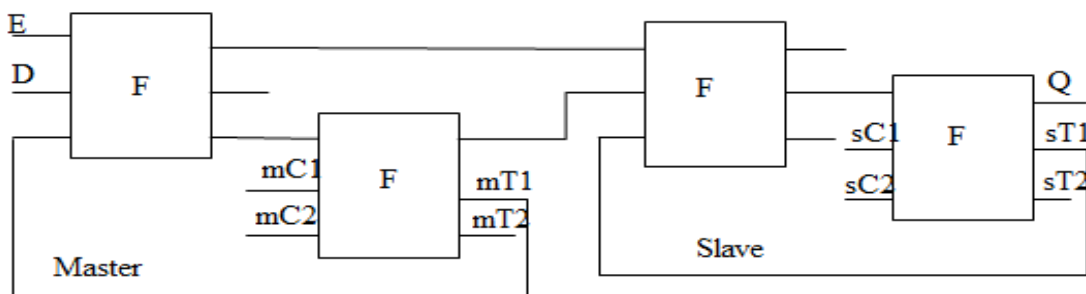


Fig 4 Fredkin gate based testable reversible master-slave D flip-flop

The testable reversible D flip-flops has four control signals  $mC1$ ,  $mC2$ ,  $sC1$  and  $sC2$ .  $mC1$  and  $mC2$  control the modes for the master latch, while  $sC1$  and  $sC2$  control the modes for the slave latch. In the normal mode, when the design is working as a master-slave flip-flop the values of the controls signals will be  $mC1=0$  and  $mC2=1$ ,  $sC1=0$  and  $sC2=1$ . In the test mode, to make the design testable with all 0s input vectors for any stuck-at-1 fault, the values of the controls signals will be  $mC1=0$  and  $mC2=0$ ,  $sC1=0$  and  $sC2=0$ . This will make the outputs  $mT1$  and  $sT1$  as 0 that results in breaking the feedback and the design becomes testable with all 0s input vectors for any stuck-at-1 fault. To make the design testable with all 1s input vectors for any stuck-at-0 fault, the values of the control signals will be  $mC1=1$  and  $mC2=1$ ,  $sC1=1$  and  $sC2=1$ . This will result in outputs  $mT1$  and  $sT1$  to have the value of 1 breaking the feedback and resulting in the design testable with all 1s input vectors for any stuck-at-0 fault.

**B. Design of double edge triggered flip-flops using fredkin gate**

The double edge triggered flip-flop stores input value at both positive and negative edges of the clock. The DET flip-flop is designed by connecting the two latches, the positive enable and the negative enable in parallel rather than in series. In Fig .5 the Fredkin gates labeled as 1 and 2 forms the positive enable D latch while the Fredkin gates labeled as 3 and 4 forms the negative enable D latch.

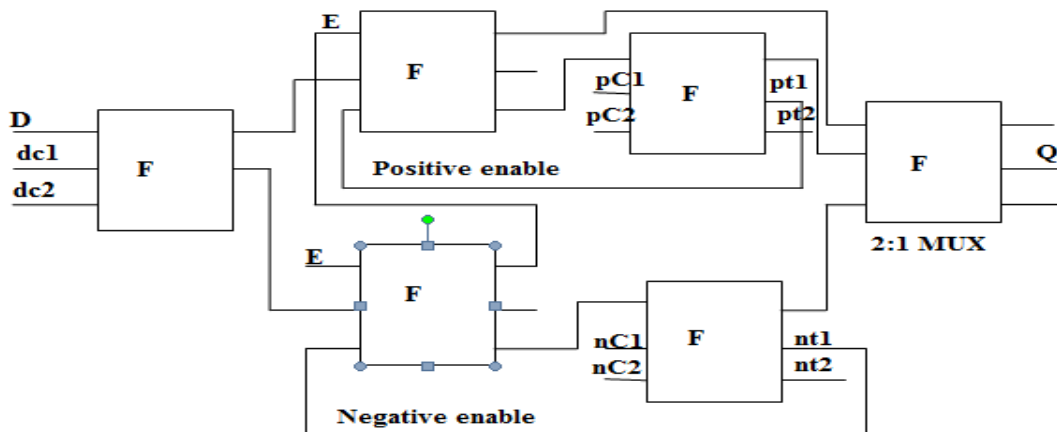


Fig 5 Fredkin gate based double edge triggered flip-flop

In the negative edge triggered master-slave flip-flop when  $E=1$  the clock is high, the master latch passes the input data while the slave latch maintains the previous state. When  $E=0$  the clock is low, the master latch is in the storage state while the slave latch passes the output of the master latch to its output. The Fredkin gate labeled as 5 works as the 2:1 MUX and transfer the output from one of these testable latches that is in the storage state to the output Q. In the design of testable reversible DET flip-flop  $pC1$  and  $pC2$  are the controls signals of the testable positive enable D latch, while  $nC1$  and  $nC2$  are the control signals of the testable negative enable D latch. Depending on the values of the  $pC1$ ,  $pC2$ ,  $nC1$  and  $nC2$  the testable DET flip-flops works either in normal mode or in the testing mode. The normal mode of the DET flip-flop in which the  $pC1=0$ ,  $pC2=1$ ,  $nC1=0$  and  $nC2=1$ .

In the test mode there are all 1 and all 0 mode. In the all 0s Test Vector as shown in Fig.5 at which the control signals will have value as  $pC1=0$ ,  $pC2=0$ ,  $nC1=0$  and  $nC2=0$ . The  $pC1=0$  and  $pC2=0$  help in breaking the feedback of the positive enable D latch while the  $nC1=0$  and  $nC2=0$  help in breaking the feedback of the negative enable D latch. This makes the design testable by all 0s test vector for any stuck-at-1 fault. In the all 1s Test Vector at which control signals will have value as  $pC1=1$ ,

$pC2=1$ ,  $nC1=1$  and  $nC2=1$ . The  $pC1=1$  and  $pC2=1$  help in breaking the feedback of the positive enable D latch, while the  $nC1=1$  and  $nC2=1$  help in breaking the feedback of the negative enable D latch. This makes the design testable by all 1s test vector for any stuck-at-0 fault.

### III. PROPOSED SYSTEM

The design of master slave flip-flop and double edge triggered flip-flop are presented using toffoli gate.

#### A. Design of testable master -slave flip-flops using toffoli gate

In this design two latches namely negative enable slave latch and positive enable slave latch are cascaded as shown in the Fig.6. The master positive enable latch is designed using the characteristic equation  $Q^+ = DE + E'Q$  with clock = 1. The slave negative enable latch is designed using the characteristic equation  $Q^+ = DE' + EQ$ . The testable reversible D flip-flops has four control signals  $mC1$ ,  $mC2$ ,  $sC1$  and  $sC2$ .  $mC1$  and  $mC2$  control the modes for the master latch, while  $sC1$  and  $sC2$  control the modes for the slave latch. In the normal mode, when the design is working as a master-slave flip-flop the values of the controls signals will be  $mC1=0$  and  $mC2=1$ ,  $sC1=0$  and  $sC2=1$ .

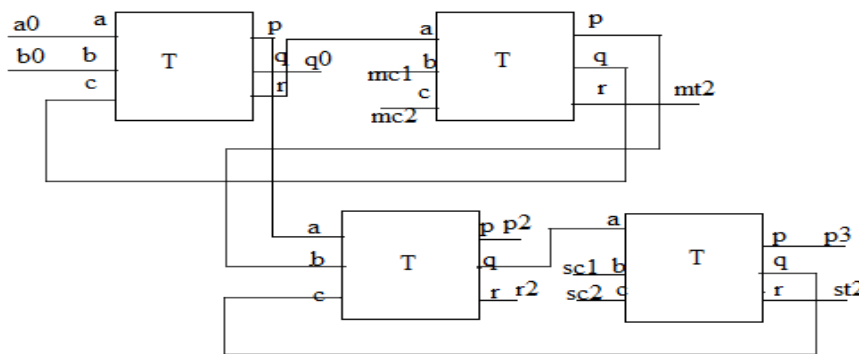


Fig 6 Toffoli gate based testable reversible master-slave D flip-flop

In the test mode, to make the design testable with all 0s input vectors for any stuck-at-1 fault, the values of the controls signals will be  $mC1=0$  and  $mC2=0$ ,  $sC1=0$  and  $sC2=0$ . This will make the outputs  $mT1$  and  $sT1$  as 0 that results in breaking the feedback and the design becomes testable with all 0s input vectors for any stuck-at-1 fault. To make the design testable with all 1s input vectors for any stuck-at-0 fault, the values of the control signals will be  $mC1=1$  and  $mC2=1$ ,  $sC1=1$  and  $sC2=1$ . This will result in outputs  $mT1$  and  $st1$  to have the value of 1 breaking the feedback and resulting in the design testable with all 1s input vectors for any stuck-at-0 fault.

#### B. Design of testable reversible double edge triggered flip-flops using toffoli gate

The DET flip-flop is designed by connecting the two latches, the positive enable and the negative enable in parallel rather than in series as shown in Fig.7. Depending on the values of the  $pC1$ ,  $pC2$ ,  $nC1$  and  $nC2$  the testable DET flip-flops works either in normal mode or in the testing mode. The normal mode of the DET flip-flop in which the  $pC1=0$ ,  $pC2=1$ ,  $nC1=0$  and  $nC2=1$ . The  $pC1=0$ ,  $pC2=1$  helps in copying the output of the positive enable D latch thus avoiding the fan out while the  $nC1=0$  and  $nC2=1$  helps in copying the output of the negative enable D latch thus avoiding the fan out. In the test mode there are all 1 and all 0 mode.

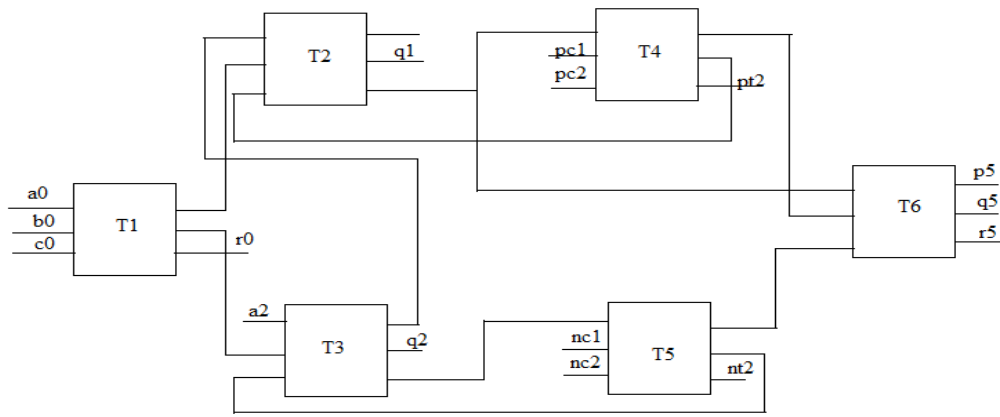


Fig 7 Toffoli gate based Double Edge Triggered flip-flop in test mode

In the all 1s Test Vector at which control signals will have value as pC1=1, pC2=1, nC1=1 and nC2=1. This makes the design testable by all 1s test vector for any stuck-at-0 fault. In the all 0s Test Vector at which the control signals will have value as pC1=0, pC2=0, nC1=0 and nC2=0. This makes the design testable by all 0s test vector for any stuck-at-1 fault.

#### IV. SIMULATION RESULTS

The simulation results for toffoli based master slave flip-flop that can detect stuck at 0 fault by setting all inputs to 1.

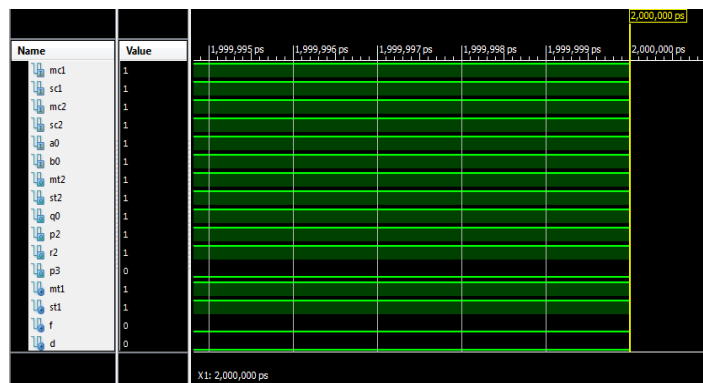


Fig 8 Waveform of toffoli based master slave flipflop

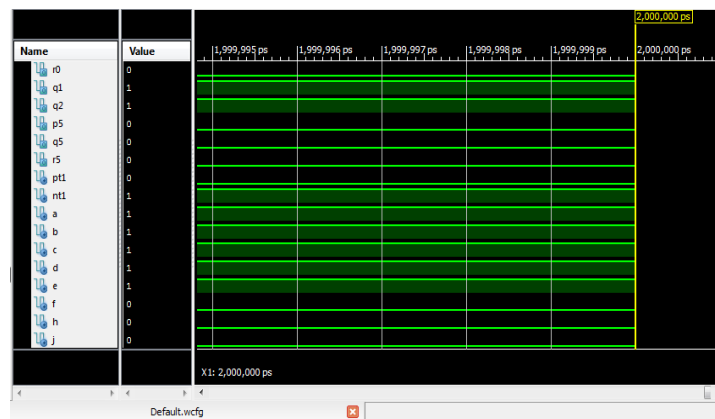


Fig 9 Waveform of toffoli based double edge triggered flip-flop

The simulation results for toffoli based double edge triggered flip-flop that can detect stuck at 0 fault by setting all inputs to 1.

## V. CONCLUSION

The reversible sequential circuits like master slave flip-flop and double edge triggered flip flop are designed using fredkin gate and toffoli gate. These circuits have less power dissipation and are used in applications like quantum computing, digital signal processing, cryptography nanotechnology and testing. The proposed reversible sequential designs are simulated verilog HDL and the waveforms are presented. This work can also be extended to the design of counter and registers.

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